

Question Bank

Year/Semester: III/ VI	Department: Electrical and Electronics Engineering	Unit : I/II/III/IV/V
Date: 17/02/2025	Subject Code/Title: EE3602-PowerSystemOperation&Control	Section : Part A/B/C
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**UNIT-I
INTRODUCTION
PART- A**

1. List out the requirements of a good power system. N-D 2022, (Nov-Dec 2021)

Planning the operation of a power system requires load studies, fault calculations, the design of means for protecting the system against lightning and switching surges and against short circuits and studies of the stability of the system. Steps to be followed.

- Planning of power system.
- Implementation of the plans.
- Monitoring of the system.

2. Define Plant capacity factor. N-D2013

This is the ratio of actual energy produced to the maximum possible energy that could have been produced during a given period.

$$\text{Capacity factor} = \frac{\text{Actual energy produced}}{\text{Maximum energy that have been produced}}$$

3. List out the various needs for frequency regulation in power system. N-D 2021, N-D2016,2013

The speed of the system is directly proportional to the frequency of the system.

$$N \propto f$$

Whenever there is change in the speed of the system, frequency of the system also varies. In order to maintain the frequency of the system in a constant level we have to undergo frequency regulation.

a. In any power system, if the frequency changes there won't be required receiving end voltage. If we connect two systems in parallel, it will spoil the system.

b. The generator turbines, particularly steam driven ones are designed to operate at a very precise speed.

c. Most of AC motors run at speeds that are directly related to the frequency.

When two systems working at different frequencies are to be tied together to make same frequency, frequency converting stations or links are required.

4. State maximum demand. M-J2014

Maximum demand is the greatest demand of load on the power station during a given period. The greatest of all "short time interval averaged" during a given period on the power station is called the maximum demand.

5. Define Plant use factor. M-J2014

Plant use factor is defined as the ratio of the actual energy generated during a given period to the product of plant capacity and the number of hours for which the plant was in operation during the period of time.

$$\text{Plant use factor} = \frac{\text{Total kWh generated}}{\text{Rated capacity of the plant} \times \text{Number of operating hours}}$$

6. Distinguish between load curve and load duration curve.N-D2014

Load factor	Diversity factor
❖ Load factor is defined as the ratio of Average load to the maximum demand During a certain period of time. ❖ The average load is less than the maximum demand; load factor is therefore, always less than unity.	❖ Maximum demand on the installation is, Therefore always less than the sum of Individual maximum demands of all consumers connected to it. ❖ The value of diversity factor will be always greater than unity.

7. Define the term Diversity factor. N-D2014

The maximum demand of all the consumers supplied from an installation do not occur usually at the same time, maximum demand on the installation is, therefore always less than the sum of individual maximum demands of all consumers connected to it.

The ratio of the sum of individual maximum demand of all the consumers supplied by it to the maximum demand of the power station is known as diversity factor.

$$\text{Diversity factor} = \frac{\text{Sum of individual maximum demand}}{\text{Maximum demand}}$$

The value of diversity factor will be always greater than unity.

8. List the significance of load factor. N-D 2022,N-D2015

Significance of Load Factor are listed as follows

- Load factor is always greater than unity, because average load is smaller than maximum demand.
- It is used to determine the overall cost per unit generated.
- If the load factor is high, cost per unit generated is low.

9. Define demand factor.N-D2015

Demand factor is the ratio of actual maximum demand on the system to the total rated load connected to the system. It is always less than the unity; the demand factor decides the maximum constraints on power system operation based on load.

$$\text{Demand factor} = \frac{\text{Maximum demand}}{\text{Connected load}}$$

Clearly, the idea of demand factor was introduced due to the fact that all the equipment connected to the system will not be worked at a time in practice and the work V A maximum demand of a group of electricity consuming devices will always be less than the capacities of the devices.

10. Classify the system load. M-J 2016

The load on a power system varies from time to time due to uncertain demands of the consumers, known as variable load on the station.

The system load in an area depends on residential commercial, industrial, agricultural, municipal and traction loads. System load variation occurs due to special events on religious and social occasions, etc.

Types of load are listed as follows:

- Lighting load
- Heating loads.
- Induction motors.
- Electronic devices.

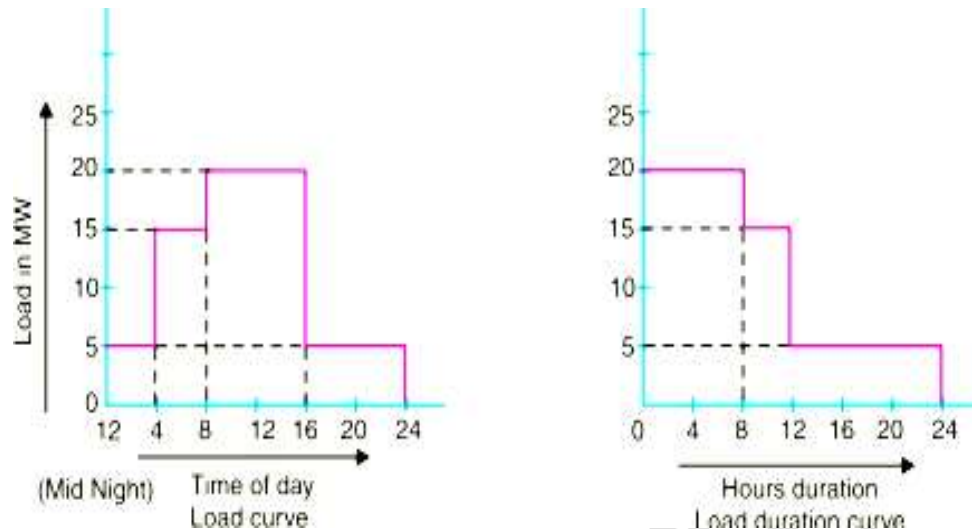
11. Define spinning reserve.N-D2018M-J2016

Spinning reserve is that generating capacity which is connected to the bus and is ready to take load.

12. Define Load Duration Curve.N-D2016

This type of curve which indicates the variation of load, but with the loads arranged in descending order of magnitude, i.e., the greatest load on the left and lesser load towards right.

From this curve, the load



13. State the need of load forecasting. N-D2018, A-M2017, 2015

- To meet out the future demand.
- Long term forecasting is required for preparing maintenance schedule of the generating units, planning future expansion of the system.
- For day-to-day operation, short term load forecasting is needed in order to commit enough generating capacity for the forecasting demand and for maintaining the required spinning reserve.
- Very short term load forecasting is used for generation and distribution. That is, economic generations scheduling and load dispatching.
- Medium term load forecasting is needed for predicted monsoon acting and hydro availability and allocating.

14. Define Black out & brownouts. A-M2017

A brownout is an intentional or unintentional drop in voltage in an electrical power supply system. Intentional brownouts are used for load reduction in an emergency. The reduction lasts for minutes or hours, as opposed to short-term voltage sag (or dip). The term brownout comes from the dimming experienced by incandescent lighting when the voltage sags. A voltage reduction may be an effect of disruption of an electrical grid, or may occasionally be imposed in an effort to reduce load and prevent a power outage, known as a blackout.

15. Define the term load curve and load duration curve. A-M 2024, N-D 2017

The curve drawn between the variations of load on the power station with reference to time is known as load curve.

This type of curve which indicates the variation of load, but with the loads arranged in descending order of magnitude, i.e., the greatest load on the left and lesser load towards right.

16. Define load forecasting in power system. N-D2017

The load on the system should be estimated in advance. This estimation in advance is known as load forecasting. Load forecasting is based on the previous experience without any historical data.

17. State the types and advantage soft computer based control in power system. A-M2015

Types: SCADA, EMS, ECC

Advantages: Computerized control systems provide benefits that can be categorized into four distinct groups:

- Time
- Money
- Information management
- Improved work conditions.

18. What are the requirements of planning the operation of a power system?

Planning the operation of a power system requires load studies, fault calculations, the design of means for protecting the system against lightning and switching surges and against short circuits and studies of the stability of the system.

Steps to be followed.

- Planning of power system.
- Implementation of the plans.
- Monitoring of the system. Compare with results

19. What is meant by Residential load and Commercial load?

Residential load: It consists of domestic lights, fans, and other appliances such as heaters, refrigerators, television, radio, air-conditioning, etc., has a high peak during evening.

Commercial load: It includes Lightings for shops, advertising hoardings, hospitals, hotels, shopping complex, theatres, etc., It has two peaks, morning and evening

Demand factor = 0.9 to 1.0;

Diversity factor = 1.1 to 1.2;

Load factor = 0.25 to 0.3

20. State the factors affecting the load forecasting. A/M2018

- To meet out future demand
- Long term forecasting – Preparing maintenance schedule of generating units, future expansion.
- Medium term – Prediction of monsoon action and hydro availability
- Short term – Spinning reserve & Unit commitment

21. Write the implications of high diversity factor and list any two methods employed to increase the diversity factor. A/M2018

- Giving incentives to some consumers to use electricity in the night or light load periods.
- Using day–light saving
- Staggering the office timings
- Having two part tariff in which consumer has to pay an amount dependent on the maximum demand of consumer uses.

UNIT–2 REAL POWER FREQUENCY CONTROL

1. State the types of ALFC for inter connected power system. N-D2017

- Flat frequency Control
- Flat tie line control
- Frequency bias tie-line control

2. Illustrate the conditions for proper synchronizing of alternators. A-M 2024, N-D2017

The conditions for operating two synchronous machines in parallel are:

- Terminal voltage must be same.
- The speed & system frequency must be same.
- Phase sequence must be same.

3. Explain the need for integral controller in ALFC. A-M2017

There is a considerable droop in speed on frequency of the turbine for a given speed changer setting. Such a large deviation (± 0.5 Hz) cannot be tolerated and we must develop some suitable control strategy to achieve much better frequency constancy. For this purpose, a signal from Δf is fed through an integrator to the speed changer. The integral controller actuates the load reference point until the frequency deviation becomes zero. Integral controller gives zero steady state error.

4. Define control area. A-M2017N-D2016, 2015, 2014

A control area is defined as a system to which a common generation control scheme is applied. The electrical interconnection within each control area is very strong as compared to the ties with the neighbouring areas. All the generators in control area swing in coherently or it is characterized by a single frequency. It is necessary to be considered as many control areas as number of coherent group. Each control area of a power system should help to maintain the frequency and voltage profile of the overall system.

5. Specify the use of static & dynamic response of the ALFC. N-D2016

Static response of an ALFC loop will inform about frequency accuracy, whereas, the dynamic response of ALFC loop will inform about the stability of the loop.

6. State the objective of tie-line bias control. A-M 2024, N-D 2022, M-J2016

The objective of tie-lines is to trade power with the systems or areas in the neighborhood whose costs for operation creates such transactions cost-effective. Moreover, even though no power is being transmitted through the tie-lines to the neighborhood systems/areas and it so happens that suddenly there is a loss of a generating unit in one of the systems. During such type of situations all the units in the interconnection experience an alteration in frequency and because of which the desired frequency is regained. Let there be two control areas and power is to be exchanged from area 1 to area 2.

7. Define area control error. N-D 2018, M-J 2016

ACE is the change in area frequency which when used in integral control loop focused the steady state frequency error to zero.

$$\text{ACE} = \Delta P_{\text{tie}} + b \Delta f \text{ p.u MW (for multi area system)}$$
$$\text{ACE} = \Delta f \text{ (for single area system)}$$

Where, b = Area frequency bias.

ΔP_{tie} is the change in tie line power,

Δf is the change in frequency.

8. State the advantage of AVR loop over ALFC. N-D2015

AVR loop is much faster than the ALFD loop and therefore there is a tendency, for the AVR dynamics to settle down before they can make themselves felt in the slower load– frequency control channel.

9. Brief the application of secondary ALFC loop in power system networks. N-D2018, A-M2015

The application of secondary ALFC loop in power system network is to maintain desired megawatt output of a generator unit and controlling the frequency of the larger interconnection. The frequency is controlled directly using ALFC so that the real power of power system is to be controlled. The frequency in interconnected system is always subject to change due to change in load and power capability of tie-line.

10. States the control objective of two area load frequency control. N-D 2014

1. Under normal operating condition, each control area should have the capacity to meet its own load from its own spinning generator, plus the scheduled interchange between the neighboring areas.
2. Under emergency conditions, the energy can be drawn from the spinning reserves of all the neighboring areas immediately due to the sudden loss of generating unit

11. State any two necessities to put alternators in parallel. M-J2014, N-D2013

1. Local or regional power use may exceed the power of a single available generation.
2. Parallel alternators allow one or more units to be shut down for scheduled or emergency maintenance while the load is being supplied with power.

12. State the assumptions made in dynamic response of uncontrolled case. M-J2014

1. Neglect the turbine dynamics
2. The speed changer action is instantaneous.

13. Define the function of load frequency control. M-J, N-D 2013

The function of load frequency control on a power system is to change the valve settings or gate openings of a prime mover as a function of load variations in order to hold system frequency at a constant level. The prime mover is controlled hence in order to that the input of turbine can be controlled easily. This is the main function of Load Frequency Control in power system. The speed governor is the main and important primary tool used in the Load Frequency Control (LFC).

14. Define Speed droop. M-J 2013

In electrical power generation, droop speed control is a speed control mode of a prime mover driving a synchronous generator connected to an electrical grid. This mode allows synchronous generators to run in parallel, so that loads are shared among generators in proportion to their power rating.

15. Why are governors employed in Power System?

Governors are employed in power systems for sensing the bias in frequency which is the result of the modification in load and eliminate it by changing the turbine inputs such as the characteristic for speed regulation (R) and the governor time constant (T_g). Governor's aim is to limit the deviation in frequency in the presence of changing active power load. Consequently, the load reference set point can be utilized for adjusting the valve/gate positions so as to cancel all the variations in load by controlling the generation of power rather than ensuing deviation in frequency through Governor employed in power system.

16. Define regulation.

Regulation is defined as percent age rise in full load at the specified power factor is switched off, the excitation being adjusted initially to give normal voltage.

$$\text{Regulation} = \frac{E_0 - V}{V}$$

Where, E_0 = No load voltage

V = On load voltage

The regulation of the real power output of the generator and its frequency (speed) is dealt by the Automatic Load Frequency Control (ALFC)

17. What are the factors to be considered for increasing response in AVR? N/D 14)

To make excitation faster, the following may be considered.

1. Provision of separate excitation for the self-excited.
2. Reduction of number of field turns to reduce the time constant.
3. Provision of new armature winding for high voltage operation.
4. Increasing the ceiling voltage by decreasing the permanent external field circuit resistance or by increasing the excitation voltage E .
5. Increase of both excitation voltage and field resistance in the same ratio, so that ceiling voltage is unaltered but time is constant.

18. List the various components in AVR loop. (A/M'08)

The various components in AVR loop are,

1. Exciter
2. Comparator
3. Amplifier
4. Rectifier
5. Synchronous generator.

UNIT-3 REACTIVE POWER CONTROL

1. Show that the shunt compensation improves critical voltage as well as the power factor. A-M 2015

Voltage stability of a system is affected by reactive power limit of the system. FACTS devices improve the reactive power flow in system thereby improving voltage stability and these are used for controlling transmission voltage, Power flow, dynamic response and reducing reactive losses in transmission lines. This paper explores the effect of SVC on static voltage stability and presents the effect of Static VAR

compensator (SVC) on Voltage Profile & Reactive Power for variable load conditions is investigated and presents static methods like Modal Analysis, Two Bus Thevenin Equivalent and Continuation Power Flow methods to predict the voltage collapse of the bus in the power system. FACTS controllers help to increase the load ability margin of the power network.

2. Distinguish between rotor angle stability and short term voltage stability. A-M 2015

Rotor Angle Stability	Short-term Voltage Stability
It is the ability of the system to remain in synchronism when subjected to a disturbance.	It is the ability of the system to maintain steady state voltages at all the system buses when subjected to a disturbance.
The rotor angle of a generator depends on the balance between the electromagnetic torque due to the generator electrical power output and mechanical torque due to the input mechanical power through the prime mover.	Unlike angle stability, voltage stability can also be a long term phenomenon.
Remaining in synchronism means that all the generator electromagnetic torque is exactly balanced by the mechanical torque.	On the other hand if voltage variations are due to slow change in load, overloading of lines, generator shifting reactive power limits, tap changing transformers etc. then the time frame for voltage stability can stretch from 1 minute to several minutes.
The main difference between voltage stability and angle stability is that voltage stability depends on the balance of reactive power demand and generation in the system whereas the angle stability mainly depends on the balance between real power generation and demand	

3. State the function of load frequency control. N-D 2017

Loading of units are allocated to serve the objective of minimum fuel cost known as automatic load scheduling.

4. State the advantages and disadvantages of synchronous compensators. N-D 2017, 2013

Advantages:

- Flexibility of operation for all load conditions.
- As the losses are considerable compared with static capacitors and the power factor is not zero.

Disadvantages:

- The cost of installation is high
- Losses of synchronous condensers are much higher compared to those of capacitors.

5. Comment on the use of series capacitors in transmission lines. A-M 2017

- The reactive power produced by the series capacitor increases with the increase in power transfer.
- Series capacitors are connected in series to compensate the inductive reactance of the line. This reduces the transfer reactance between the buses to which the line is connected.
- It increases maximum power that can be transmitted and reduces reactive power loss.

6. Define exciter ceiling voltage. A-M2017

- It is the maximum voltage that may be attained by an exciter under specific conditions.
- The voltage of the main exciter should be controlled from zero to ceiling voltage, the maximum voltage that may be attained by the exciter under specified conditions, to obtain rapid correction of exciter voltage after disturbance or fault.

7. State the various functions of an excitation system. N-D2016, 2013

The basic function of an excitation system is to

- Provide necessary direct current to the field winding of the synchronous generator.
- The excitation system must be able to automatically adjust the field current to maintain the required terminal voltage. The DC field current is obtained from a separate source called an exciter. The excitation systems have taken many forms over the years of their evolution.

8. Mention the purpose of series compensation. N-D2016

Purpose of series compensation:

- Increase in Power Transfer Capability
- Improvement in System Stability
- Load Division among Parallel Line
- Control of Voltage

9. Define SVC. M-J2016

SVC comprises of switched or fixed capacitor bank and switched reactor bank in parallel. These compensators draw reactive power from the line thereby regulating voltage, improve stability (steady state and dynamic), control overvoltage and reduce voltage and current unbalances. In HVDC application these compensators provide the required reactive power and damp out sub harmonic oscillations. Static VAR compensators use switching for VAR control. These are also called static VAR switches or systems.

10. Explain how voltage and reactive power are interrelated. M-J2016, 2013

- Voltage control in an electrical power system is important for proper operation for electrical power equipment to prevent damage such as overheating of generators and motors, to reduce transmission losses and to maintain the ability of the system to withstand and prevent voltage collapse.
- In general terms, decreasing reactive power causing voltage to fall while increasing it causing voltage to rise. A voltage collapse occurs when the system tries to serve much more load than the voltage can support.
- When reactive power supply is lower, voltage drops, current must increase to maintain power supplied, causing the system to consume more reactive power and the voltage drops further.
- If the current increases too much, transmission lines go offline, overloading other lines and potentially causing cascading failures.

11. State the role of exciter. N-D2015

The exciter is the main component in the AVR loop. It delivers the DC power to the generator field. It must have adequate power capacity and sufficient speed of response (rise time less than 0.1 sec). The exciter control is the major important concern in the reactive power control of power system. By controlling the voltage, it can control the reactive power. The main function of the exciter is to provide Direct Current to the synchronous motor. The control functions which are provided for exciter are control of voltage and reactive power flow and the enhancement of system stability.

12. Define stability compensation. N-D2015

Compensation consists of injecting reactive power to improve power system operation to keep voltages close to nominal values. It reduces the line currents and hence network losses then improves the stability enhancement. It compares the Generator terminal voltage with a preset reference voltage. If the Generator terminal voltage is less than the reference voltage, the AVR increases D.C. voltage across the Generator field, maintaining the constant voltage as per the setting. Stability compensation improves the dynamic response characteristics without affecting the static loop gain.

13. State the relation between voltage, power and reactive power at a node. N-D 2014

The voltage drop in the transmission line is directly proportional to the reactive power flow (Q-flow) in the transmission line. Most of the electric load is inductive in nature. In a day, during the peak hours, Q-flow will be heavy, resulting in more voltage drop. However, during off-peak hours, the load will be very small and the

distributed shunt capacitances throughout the transmission line become predominant making the receiving-end voltage greater than the sending-end voltage (Ferranti effect). Thus during off-peak hours there may be a voltage rise in the transmission line from sending-end to receiving-end.

$$\frac{\partial Q}{\partial V} = \frac{E-2V}{X} \quad \text{If } X \text{ is small, } \frac{\partial Q}{\partial V} \text{ is large}$$

14. State the advantages of Switched capacitors in voltage control. N-D2018, 2014

The SC behaves like a resistor whose value depends on capacitance C and switching frequency f . The SC

resistor is used as a replacement for simple resistors in integrated circuits because it is easier to fabricate reliably with a wide range of values. It also has the benefit that its value can be adjusted by changing the switching frequency (i.e., it is a programmable resistance).

- Power factor improvement.
- Efficiency of transmission and distribution of power is high.
- Reactive power compensation.
- Less costly.
- Improve feedervoltage control.

15. Where are synchronous condensers installed? M-J2014

In Industries in order for Power factor correction and need to maintain Power factor within limits.

16. State the different types of static VAR compensators. N-D2018, M-J2014

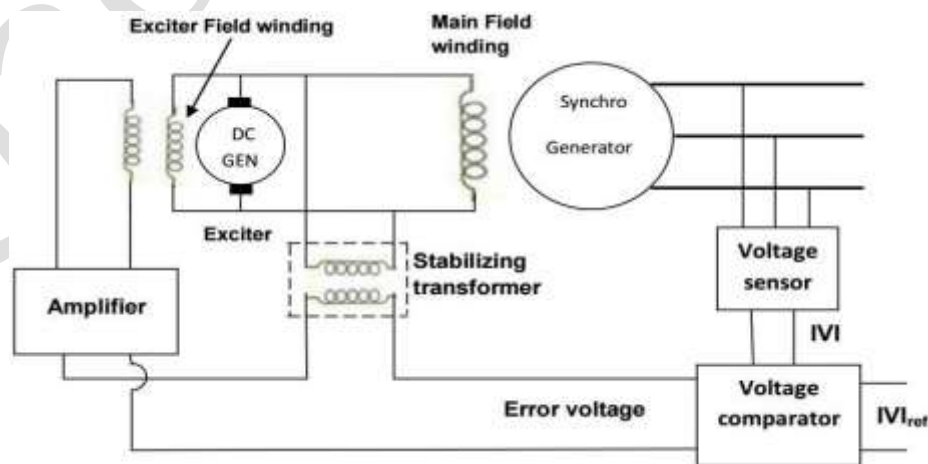
- Saturated Reactors [SR]
- Thyristor Controlled Reactors [TCR]
- Thyristor Switched Capacitors [TSC]
- Thyristor Controlled Transformers [TCT]
- Thyristor Switched Capacitors [TSC]

17. State the functions of AVR. M-J2013

The function of the Automatic Voltage Regulator (AVR) is to maintain constant voltage and power line conditioning to the load under a wide variety of conditions, even when the utility input voltage, frequency or system load vary widely.

The Automatic Voltage Regulator (AVR) is mainly responsible for regulating system voltage without violating the limit which indirectly controls the reactive power of a system.

18. Draw the typical block diagram of DC excitation system.



DC excitation system utilizes DC generators as sources of excitation power and provide current to the rotor of the synchronous machine through slip rings.

19. Write the different methods of voltage control.

The different methods of voltage control are,

- Excitation control,
- Static Shunt capacitors
- Static Shunt reactor,
- Synchronous compensator
- Tap changing transformer,
- Booster Transformer,
- Regulating Transformer and
- Static VAR compensator.

20. Write the objectives of FACTS controllers in the power system network and the main areas of application of FACTS devices.

Objectives of FACTS controllers

- Better the control of power flow (Real and Reactive) in transmission lines.
- Limits SC current
- Increase the loadability of the system
- Increased dynamic and transient stability of power system
- Load compensation
- Power quality improvement

FACTS mainly find application in following areas,

- Power transmission
- Power Quality
- Railway Grid Connection
- Wind power grid Connection
- Cable Systems

21. State the main objective of Reactive power and voltage control in power system. A-M 2024, A-M 2018

For efficient and reliable operation of power systems should have the following.

- All machines are designed to operate at a certain voltage—Above/below rated voltage caused damage to them
- System stability is increased due to maximum utilization of transmission line.
- Reactive power flow is minimized so as to reduce I^2R and I^2X losses and to operate the transmission system efficiently.

22. Outline the role of Synchronous generators adopted for generation and absorption of reactive power. A-M 2018

Over excited – Generate Reactive

power Under excited –

Absorption of reactive power

UNIT-4– UNIT COMMITMENT & ECONOMIC DISPATCH**1. Find the incremental transmission losses for a two area power system, where the bus voltages are kept fixed and the line power flow is a function of line angle. Power loss is a function of generation of area B only. A-M 2015**

It is evident that,

$$P_l = f(P_{gB})$$

This also suggests that the incremental transmission loss for grid A will be zero and the incremental transmission loss of the line will be governed by the grid B only.

Thus,

Economic operation being dictated by the criterion,

$$\lambda = \frac{(IFC)_A}{1 - (ITL)_A} = \frac{(IFC)_B}{1 - (ITL)_B}$$

In this case for economic operation,

$$\lambda = \frac{(IFC)A}{1-0} = \frac{(IFC)B}{1-(ITL)B}$$

2. Define spinning reserve. A-M 2015, M-J 2014, 2015

Spinning reserve is the total amount of generation availability from all units synchronized on the system minus the present load and losses being supplied.

Spinning Reserve = [Total amount of generation] – [Present Load + Losses]

Spinning reserve must be established, so that the loss of one or more units does not cause drop in system frequency. (i.e. if one unit is lost, the spinning reserve unit has to make up for the loss in a specified time period.

Spinning reserve is the reserve generating capacity running at zero load or no load.

3. Define FLAPC. N-D 2017, 2013

FLAPC - Full Load Average Production Cost

Full load average production cost = {net heat rate at full load} * {fuel cost}

$$FLAPC = \frac{C_i(Q) \cdot K \cdot H_i(Q)}{\bar{P}_{Gi}} \quad P_{Gi}$$

4. State the conditions for the optimal power dispatch in a lossless system. N-D 2017, 2013

The necessary condition for the existence of a minimum cost operating condition is that the incremental cost of all the units be equal to some undetermined value (λ) called Lagrangian multiplier.

$$\lambda_i = \frac{dF_i}{dP_i}$$

5. State the constraints in unit commitment. A-M 2017, N-D 2014

- Spinning reserve constraints
- Thermal unit constraints are,
 - Minimum up time
 - Minimum downtime &
 - Crew constraints.
- Other Constraints
 - Hydro Constraints
 - Must Run Constraint
 - Fuel Constraint

For a single value turbine, the governing is done by throttling of steam and for such units, the input-output curve is substantially a straight line within its operating range.

6. Define incremental cost in power dispatch. A-M 2017

$$\text{Incremental Cost} = \frac{\text{Small change in input}}{\text{Small change in output}} = \frac{dC_i(P_{Gi})}{dP_{Gi}}$$

7. Write the coordination equation taking the effect of transmission losses. N-D 2016

In this case for economic operation,

$$\lambda = \frac{(IFC)_A}{1 - 0} = \frac{(IFC)_B}{1 - (ITL)_B}$$

8. Write the relationship between fuel energy input and input fuel cost, give the quadratic expression of fuel cost.

Relationship between fuel energy input and input fuel cost

Input fuel cost $F_i(P_i) = K \cdot F_i(P_i)$ Rs/hr

Where, K = Cost of the fuel in Rs/MKcal.

$F_i(P_i)$ = Fuel energy input in MKcal/hr.

Quadratic expression of fuel cost

$F_i(P_i) = \alpha_i(P_i) + \beta_i(P_i) + \gamma_i$ Rs/hr

Where $\alpha_i, \beta_i, \gamma_i$ are constants.

(P_i) = Power generation.

9. Define priority list method. M-J 2016

Priority list method is the simplest unit commitment solution method which consists of creation a priority list of units.

The priority list can be obtained by noting the full-load average production cost of each unit.

Full load average production cost = {net heat rate at full load} * {fuel cost}

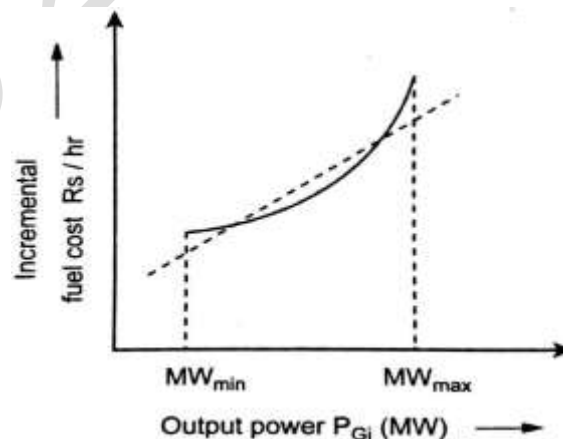
$$FLAPC = \frac{C_i(P)}{P_{Gi}} = \frac{K \cdot H_i(P_{Gi})}{P_{Gi}}$$

10. Define incremental transmission loss. M-J 2016

$$\frac{\partial PL_L}{\partial P_{Gi}} = ITL$$

11. Draw incremental fuel cost curve. N-D 2015, M-J 2015, 2016

The slope of fuel cost curve i.e., $\frac{dC_i}{dP_{Gi}}$ Rs/MW can be obtained by differentiating equation with respect to P_{Gi} .

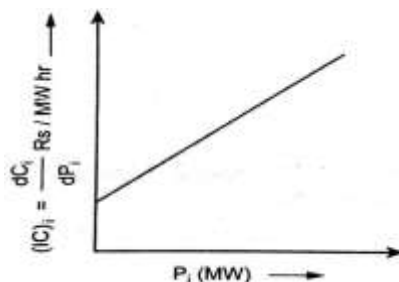


12. Define crew constraints. N-D 2018, 2015

If a plant consist of two (or) more units, all the units cannot be turned on at the same time since there are not enough crew members to attend both units while starting up. In a plant with more than one unit there may not be enough personnel to attend both the units if both are turned on or off at the same time and hence at the same time both cannot be turned on or off. A certain amount of energy is expended to bring the unit on-line. This is not generated and is included in the unit commitment problem as a start-up cost.

13. Draw the incremental cost curve of thermal unit. N-D2014

Incremental cost curve of thermal unit is plotted with the derivative of the fuel cost curve versus real power



14. Write the equality and inequality constraints considered in the economic dispatch problems (N/D'11)

The power system has to satisfy several constraints while in operation. These may be broadly divided into two types,

Equality constraints:

The first of these arises out of the necessity for the system to satisfy load balance and are called equality constraints.

Inequality constraints:

A number of other constraints due to physical and operational limitations of the units and components will arise in economic scheduling. These are in the form of inequality constraints.

Each generator in operation will have a minimum and maximum permissible output and the production must be constrained to ensure that

$$P_{1\min} < P_1 < P_{1\max}$$

15. Distinguish between economic dispatch & unit commitment. N-D2018, A-M2018, M-J2014

Economic Dispatch	Unit Commitment
Optimum allocation of generation to each station. (At each generating station at various station load levels)	Optimum allocation of number of units to be operated (to determine the units of a plant that should operate for a given load is the problem of unit commitment)
The problem assumes that there are „n“ units already connected to the system.	There are number of subsets of the complete set of „n“ units that would satisfy the expected demand.
Purpose of economic dispatch problems is to find the optimum operating policy for these „n“ units.	Purpose of unit commitment is to find the optimal subset among the subsets which provide the minimum operating cost.

16. Write the condition for minimum uptime. (A/M'11)

Once the unit is running, it should not be turned off immediately. This is the condition for minimum uptime. Generally more generators are started up around the peak load, and few units are started up at light loads based on full load average production cost. To satisfy minimum up time constraint the units are set continuously in ON condition.

17. List the techniques for the solution of the unit commitment problem.

The various techniques involved in unit commitment problem are listed as follows. They are,

- Priority list method
- Dynamic programming
- Brute force technique.

A recent literature review identified nine of these methodologies: priority list method, dynamic programming, Lagrangian relaxation, genetic algorithms, simulated annealing, particle swarm optimization, fuzzy logic algorithm, and evolutionary programming.

18. List out the reasons for choosing the LR algorithm. (A/M'13)

- Specified for the Unit Commitment Program.
- Flexible in dealing with various types of constraints.
- Flexible to incorporate additional coupling constraints that have not been considered so far.
- Flexible because no priority ordering is imposed

Computationally much more attractive for large system since the amount of computation varies with the number of units.

19. What is the need of economic dispatch control?

- a. Economic dispatch determines the best way to minimize the current generator operating costs.
- b. The λ -iteration method is a good approach for solving the economic dispatch problem:
 - i. Generator limits are easily handled.
 - ii. Penalty factors are used to consider the impact of losses.
- c. Economic dispatch is not concerned with determining which unit to turn on/off (this is the unit commitment problem).

Basic form of economic dispatch ignores the transmission system limitations.

20. Relate the necessary condition for the existence of minimum cost operation for the thermal power system. A-M2018.

- Optimal Loading
- Regular Maintenance
- Adopt energy efficient equipment and process.

UNIT-5 COMPUTER AIDED CONTROL OF POWER SYSTEM

1. State the role of SCADA plays in electrical power systems. A-M2015

Modern SCADA systems are already contributing and playing a key role at many utilities towards achieving:

- New levels in electric grid reliability – increased revenue.
- Proactive problem detection and resolution – higher reliability.
- Meeting the mandated power quality requirements – increased customer satisfaction.
- Real-time strategic decision making – cost reductions and increased revenue

2. Define the responsibilities of regional load dispatch centre. A-M2015

The main responsibilities of RLDCs are:

- ◆ System parameters and security.
- ◆ To ensure the integrated operation of the power system grid in the respective region.
- ◆ System studies, planning and contingency analysis.
- ◆ Daily scheduling and operational planning.
- ◆ Facilitating bilateral and inter-regional exchanges.
- ◆ Computation of energy dispatch and draw values using SEMs.
- ◆ Augmentation of telemetry, computing and communication facilities.

3. Define SCADA. N-D2017

SCADA stands for supervisory control and data acquisition system. It allows a few operators to monitor the generation and high voltage transmission systems and to take action to correct overloads. The supervisory system may be combined with a data acquisition system by adding the use of coded signals over communication channels to acquire information about the status of the remote equipment for display or for recording functions. It is a type of industrial control system (ICS).

4. Define State estimation. N-D2017, M-J2016, N-D2013, M-J2013

State estimation is defined as the process of assigning a value to an unknown system state variable based on the measurements from that system according to some criteria.

1. Real-time data primarily come from SCADA
2. SE supplements SCADA data: filter, fill, smooth.
3. To provide a consistent representation for power system security analysis

5. List out the conditions for normal operation of a power system. A-M 2017

- Controller needs to operate the system as economic.
- Voltage & Frequency are needed to keep close to normal.

6. Define energy control centre. A-M 2024, A-M 2017

When the power system increases in size, their operation and interaction become more complex. So, it becomes essential to monitor this information simultaneously for the total system which is called Energy Control Centre.

7. State the functions of SCADA. N-D 2016, M-J 2016, N-D 2013, M-J 2013

The data acquisition and control system performs the following general functions.

- a. Data acquisition and validation,
- b. Real-time variable computations,
- c. Alarm monitoring and display,
- d. Performance and deviation calculation,
- e. Trends, events, reports and logs,
- f. Sequential control,
- g. Modulating control
- h. Other related functions.

8. State the major functions that are carried out in an operational control centre. N-D 2016

- System Load Forecasting-Hourly energy, 1 to 7 days.
- Unit commitment-1 to 7 days.
- Economic dispatch
- Hydro-thermal scheduling-up to 7 days.
- MW interchange evaluation-with neighbouring system
- Transmission loss minimization
- Security constrained dispatch
- Maintenance scheduling, Production cost calculation

9. Explain the states of power system. N-D 2015

- Normal state
- Alert state
- Emergency state
- Extreme state
- Restorative state

10. State the functions of control centre. N-D 2015

Functions of Control Centre.

- System Monitoring
- Data Acquisition and Control

11. Define power system security. N-D 2014

It is defined as the degree of risk in the ability to survive imminent disturbances (contingencies) without interruption of customer service.

It depends upon the reserve capacity available in a given situation and the contingency probability of a disturbance.

12. List the applications of SCADA. N-D 2014

As the power system deals with power generation, transmission and distribution sectors, monitoring is the main aspect in all these areas. Thus the SCADA implementation of power system improves

- The overall efficiency of the system for optimizing
- Supervising and controlling the generation and transmission systems,
- Greater system reliability and
- Stability for integrated grid operation.

13. State the objectives of AGC.M-J2014

The objectives of AGC are

- To hold frequency at or very close to a specified normal value.
- To maintain the current value of interchange power between control areas.
- To maintain each unit's generation at the most economic value.

14. Define restorative state.M-J2014

To bring the extreme state back to normal through the restorative state, this is a slower process.

From this state, the system may be brought back either to alert state or secure state. The latter is a slow process. Hence, in certain cases, first the system is brought back to alert state and then to the secure state. This is done using restorative control action.

15. Define Network Topology in a Power System.

In order to run the state estimation, we must know how the transmission line is reconnected to the load and generation buses. This information is called network topology.

16. List out the functions of Energy management system. A-M 2024, A-M2018

- System Load Forecasting-Hourly energy, 1 to 7 days.
- Unit commitment-1 to 7 days.
- Economic dispatch
- Hydro-thermal scheduling-up to 7 days.
- MW interchange evaluation-with neighboring system
- Transmission loss minimization
- Security constrained dispatch
- Maintenance scheduling
- Production cost calculation.

17. Point out the objectives of Load Frequency Control.

Load frequency control (LFC) has to achieve three primary objectives, which are stated below in priority order:

- To maintain frequency at the scheduled value.
- To maintain net power interchange with neighbouring control areas at the scheduled values.
- To maintain power allocation among units at economically desired values.

18. Write about RTU and Master Station in SCADA.

Remote Terminal Units (RTU): RTUs are microprocessor controlled electronic devices deployed in field at specific sites and locations. They collect necessary data and transmit them to SCADA for processing.

Master Unit: It is a large computer system which serves as a central processor.

Communication Links: Fibre optic/satellite/microwave communications are employed to link RTUs with SCADA.

19. List out the National Regional Electricity Boards.

The national regional electricity boards are,

- Northern Regional Electricity Board
- Western Regional Electricity Board
- Southern Regional Electricity Board
- Eastern Regional Electricity Board
- North-east Regional Electricity Board

20. State the Weighted Least Square Criterion.A-M2018,N-D2018

The objective is to minimize the sum of the squares of the weighted deviations of the estimated measurements $[F(X)]$ from the actual measurements $[Z]$.

21. What are the priorities for operation of modern power system? N-D 2018

- Economic Operation
- Frequency Regulation
- Voltage Regulation
- Power factor maintenance
- Load forecasting and Scheduling
- Ability to Restructure.

PART– B

UNIT 1

1. What are the components of speed governor system of an alternator? Derive a transfer function and sketch a block diagram.
2. With neat sketch describe the P-F and Q-V control structure. N-D 2022
3. Briefly discuss the classification of loads and list out the important characteristics of various types of loads.
4. Problem (Load Curve)
5. Explain the method availabilities for providing economic operation of power system.
6. Write short notes on load v curve load duration curve energy curve.
7. Explain about spinning reserve, hot reserve, cold reserve.
8. What is load forecasting? also discuss about the computational methods available for it. A-M 2024
9. Explain the necessity of voltage and frequency regulation in power system. A-M 2024

UNIT 2

1. Explain load frequency control.
2. Draw the block diagram of LFC control of single area and derive the dynamic response.
3. Develop the block diagram model of uncontrolled two area load frequency control system and explain the salient features under static conditions. A-M 2024
4. Explain Interconnected operation.
5. Explain the solution technology for solving priority list method by dynamic programming method.
6. Explain the static state estimation of power system.
7. List out the components of speed governor system of an alternator derive its transfer function with the help of block diagram. A-M 2024, N-D 2022

UNIT 3

1. Draw the circuit diagram for a typical excitation system and derive the transfer function model and draw the block diagram.
2. Discuss generation and absorption of reactive power.
3. Explain different types of static VAR compensators with a phasor diagram.
4. Discuss about the various methods of voltage control. A-M 2024
5. Derive the relations between voltage, power and reactive power at a node for applications in power system control.

UNIT 4

1. Derive the coordination equation with losses neglected.
2. Derive the coordination equation of an 'n' bus power system taking into account the effect of system losses.
3. Derive the expression for base point and participation method.
4. State the unit commitment problem. With the help of flowchart explain forward dynamic programming solution method. A-M 2024
5. Explain Priority list method using full Load average production cost. State the merits and demerits.
6. Numerical problems in economic dispatch & unit commitment A-M 2024

UNIT 5

1. Briefly discuss the various functions of energy control centre.
2. Explain the different operating states of power system with state transition diagram.
3. Explain the hardware components of SCADA with neat diagram and also mention the functions of it. A-M 2024
4. Explain about power system security
5. What is EMS? What are its major functions in power system operation and control? A-M 2024

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HoDRemarks: